Towards a classification of surgical skills using affine velocity

F.A. Prieto Ortiz; J. Cifuentes Quintero; M.T. Pham; P. Boulanger; R. Moreau

Abstract-

The aim of this study is to determine if navigation movements, used in surgical training, follow a particular power law which describes the relationship between the hand trajectory's curvature, torsion, and speed. Based on this approach, this study proposes the affine velocity as an appropriate classification feature to solve the surgical movement recognition problem. Eight subjects with different surgical experience were involved in the experiments. They were asked to do two kinds of movements that involve depth perception skills with their right arm. Using six video cameras and an instrumented laparoscope, the 3D trajectory of the end effector was recorded for each participant. A power law was used to fit the data sets and the exponents that relate the torsion, curvature, and speed were calculated. The exponents involved and the affine velocity for each trajectory were then computed, using a multi-variable linear regression, and compared between participants. It is shown that fitting residual follows a normal distribution indicating no regression biases. Finally, it is presented that an affine velocity analysis could be able to classify between both trajectories showing a correlation with the surgical skills and a clear difference for people with some surgical training.

Index Terms-

Due to copyright restriction we cannot distribute this content on the web. However, clicking on the next link, authors will be able to distribute to you the full version of the paper:

Request full paper to the authors

If you institution has a electronic subscription to IET Science, Measurement & Technology, you can download the paper from the journal website: Access to the Journal website

Citation:

Boulanger, P.; Cifuentes, J.; Moreau, R.; Pham, M.T.; Prieto, F. "Towards a classification of surgical skills using affine velocity", IET Science, Measurement & Technology, vol.12, no.4, pp.548-553, July, 2018.